L Number	Hits	Search Text	DB	Time stamp
-	2	JP-2000288974-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/01/14 13:13
-	5	JP-05127722-$.did. JP-07270137-$.did. JP-07319525-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/01/14 13:16
-	97	(382/153).CCLS.	USPAT; US-PGPUB	2003/01/14 13:20
-	163	(382/152).CCLS.	USPAT; US-PGPUB	2003/01/14 13:42
-	31	((382/152).CCLS.) and robot	USPAT; US-PGPUB	2003/01/14 13:49
-	43	((382/151).CCLS.) and robot	USPAT; US-PGPUB	2003/01/14 13:49
-	44	(robot) same (plural$3 or multiple or dual or two or several or many) adj (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj piece or part or model)	USPAT; US-PGPUB	2003/01/14 16:04
-	2	JP-2000288968-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/01/14 15:12
-	7	arimatsu-taro.in.	USPAT; US-PGPUB	2003/01/14 15:13
-	108	watanabe-atsushi.in.	USPAT; US-PGPUB	2003/01/14 15:17
-	314	(382/151).CCLS.	USPAT; US-PGPUB	2003/01/14 15:49
-	2317	(382/141-154).CCLS.	USPAT; US-PGPUB	2003/01/14 15:49
-	1	JP-04075887-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/01/14 15:56
-	580	(382/154).CCLS.	USPAT; US-PGPUB	2003/01/14 15:56
-	7	((382/154).CCLS.) and (reference or register$3 or registration or teach$3 or train$3 or learn$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot	USPAT; US-PGPUB	2003/01/14 16:28
-	55	(robot) same (video or camera or CCD or image or visual) same (predetermined or known or specifi$2 or determined) near distance	USPAT; US-PGPUB	2003/01/14 16:16
-	23	robot same (2-D or two-D or two-dimension$2 or "2"-dimension$2 or bi-dimensional or (two or "2") adj dimension$2) with distance	USPAT; US-PGPUB	2003/01/15 09:04
-	15	robot same (reference or register$3 or registration or teach$3 or train$3 or learn$3) same (video or camera or CCD or image or visual) same (predetermined or known or specifi$2 or determined) near distance	USPAT; US-PGPUB	2003/01/15 09:24